

TEMPERATURE CONTROLLER/ CONTROLLER PROGRAMMER



33 X 72

Model KR1/KR3

Quick Guide • ISTR-FKR_ENG03



Dr. Siebert und Kühn GmbH & Co. KG
Struthweg 7-9 - 34260 Kaufungen
Tel.: +49 5605 803-0, Fax: +49 5605 803-54
Internet site: www.sika.net
E-mail: info@sika.net

MODEL CODE

The Hardware resources are identified by the following Model Code.

Model: KR # [ABCDEFGHI] - [0000]

Line	KR	#
Controller (+ timer)	1	
Controller (+ timer + programmer)	3	
Optional functions		
None	-	
Timer	T	
Programmer + Timer KR3 only	P	
Power Supply		
100... 240Vac (-15... +10%)	H	
24Vac (-25... +12%) or 24Vdc (-15... +25%)	L	
Input		
TC, Pt100, Pt1000, mA, mV, V + Digital Input 1	C	
TC, NTC, PTC, mA, mV, V + Digital Input 1	E	
Output OP1		
Relay (1 SPST NO, 4 A/250 Vac)	R	
VDC for SSR (12 Vdc/20 mA)	O	
Analogue Output (0/4... 20 mA, 0/2... 10 V) KR3 only	I	
Output OP2		
None	-	
Relay (1 SPST NO, 2 A/250 Vac)	R	
VDC for SSR VDC (12 Vdc/20 mA)	O	
Relay (1 SPST NO, 2 A/250 Vac) KR3 servomotor drive only (note)	M	

MANUAL RETRIEVAL

KR1/KR3 are panel mounting, Class II instruments. They have been designed with compliance to the European Directives. All information about the controller use can be found in the Engineering Manual: ISTR-MKR_ENG0x ("x" is the revision). The manual of the controller can be downloaded (free of charge) from the web-site:

www.sika.net

To download the operating instructions, go through the main menu on Products -> Electronic Measuring and Calibration Instruments -> Electronic controllers and indicators -> Controller Series CON.

Here you can select the desired product. The tab "Documents" contains the current operating instructions in PDF format.

Warning!

- Whenever a failure or a malfunction of the device may cause dangerous situations for persons, things or animals, please remember that the plant must be equipped with additional devices which will guarantee safety.
- We warrant that the products will be free from defects in material and workmanship for 18 months from the date of delivery. Products and components that are subject to wear due to conditions of use, service life and misuse are not covered by this warranty.

Warning!

Some order codes present in the tables that follow (Digit A: Code T and P, Digits E and F: Code M) are fully described in the "Engineering Manual" that can be freely downloaded from Sika web site.

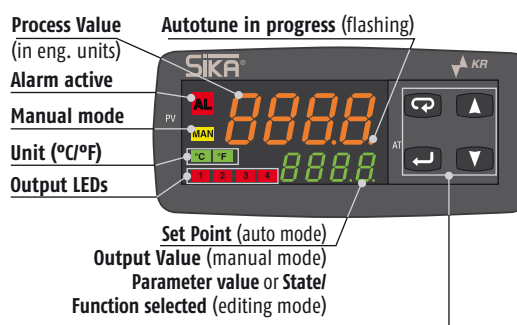
Output OP3	F
None	-
Relay (1 SPST NO, 2 A/250 Vac)	R
VDC for SSR (12 Vdc/20 mA)	O
Relay (1 SPST NO, 2 A/250 Vac) KR3 servomotor drive only (note)	M
Output OP4	
Digital I/O (see the Electrical Connections paragraph for details)	D
Serial Communications	
TTL	-
RS485 Modbus	S
Terminal Type	
Standard (screw type non removable terminal blocks)	-
With plug-in screw type terminal blocks	E
With plug-in clamp type terminal blocks	M
With plug-in terminal blocks (fixed part only)	N

Note: For servomotor drive, both OUT2 and OUT3 codes must be selected as "M".

Model Code example: KR3-HCRRRD--

Controller KR3, no timer, no programmer, 100... 240 Vac, TC/Pt100/Pt1000/mV/V + Digital Input 1, 3 Relay Outputs, Output 4, TTL, non removable screw type terminals.

DISPLAY AND KEYS

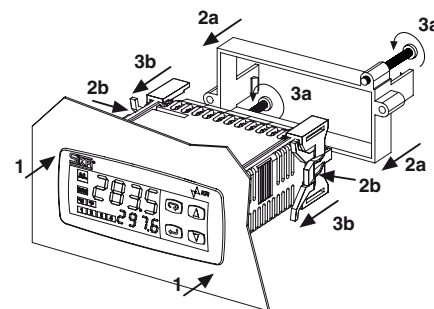


	Operator Mode	Editing Mode
Access to: - Operator Commands (Timer, Setpoint selection ...) - Parameters - Configuration	Confirm and go to Next parameter	
Access to: - Operator additional information (Output value, running time ...)	Increase the displayed value or select the next element	
Access to: - Set Point	Decrease the displayed value or select the previous element	
Start the programmed function (Autotune, Auto/Man, Timer ...)	Exit from Operator commands/Parameter setting/Configuration	

DIMENSIONS

Overall dimensions (L x H x D): 78 x 35 x 69.5 mm
(3.07 x 1.37 x 2.73 in.)
Panel Cut-out (L x H): 71+0.6 x 29+0.6 mm
(2.79+0.023 x 1.14+0.023 in.)

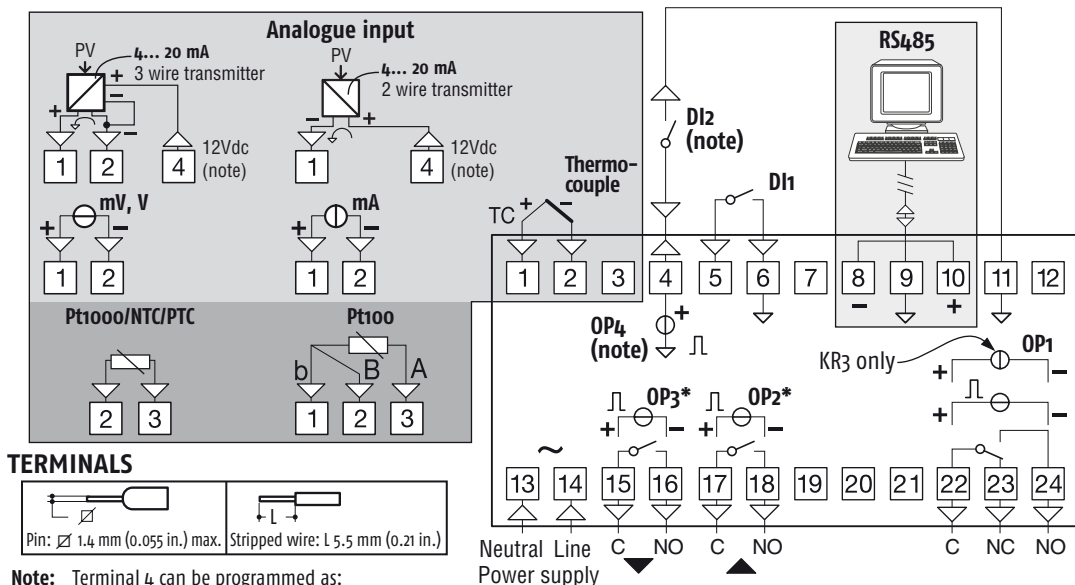
MOUNTING



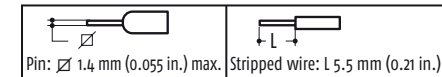
Attention

The controller can be installed using 2 different types of brackets. Follow the sequence 1, 2a, 3a for the closed version of the bracket, the sequence 1, 2b, 3b for the 2 pieces bracket type.

ELECTRICAL CONNECTIONS



TERMINALS

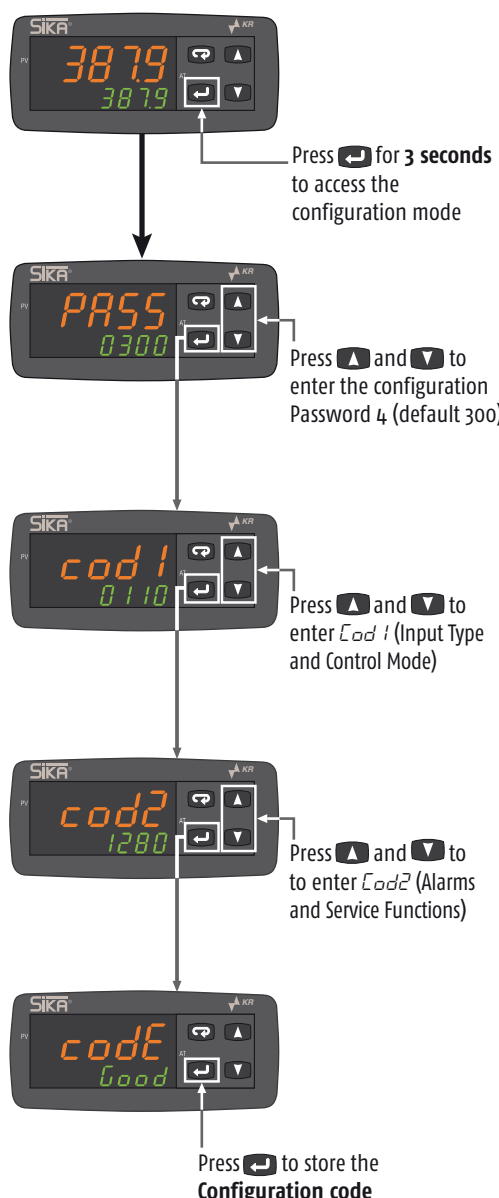


- Note: Terminal 4 can be programmed as:
- Digital Input (DI2) connecting a free of voltage contact between terminals 4 and 11;
 - 0... 12 V SSR Drive Output (OP4) connecting the load between terminals 4 and 11;
 - 12 Vdc (20 mA) transmitter power supply connecting the 2 wire transmitter between terminals 4 and 1; for 3 wire transmitter connect terminal 4 to transmitter power supply input and terminal 1 and 2 to transmitter signal output.

* For KR3 servomotor drive: OP2 = open, OP3 = close.

Supply voltage: 100... 240 Vac/
18... 28 Vac/
20... 30 Vdc

HOW TO SET THE CONFIGURATION CODE



Note: To leave the Configuration session without saving the settings made, press the key

CONFIGURATION CODE

The KR instruments can be easily configured by the "Code Configuration" method for the most common requirements, just entering two 4-digit codes: Cod1 [LMNO] for the Input Type and Control Mode selection and Cod2 [PQRS] for the Alarms and the Service Functions.

For complete controller configuration see the Engineering Manual.

Note: Before starting the configuration code setting, please define and write down Cod1 and Cod2 as needed:

Input Type and Range	L	M
TC J	-50... +1000°C	0 0
TC K	-50... +1370°C	0 1
TC S	-50... +1760°C	0 2
TC R	-50... +1760°C	0 3
TC T	-70... +400°C	0 4
Infrared J	-50... +785°C	0 5
Infrared K	-50... +785°C	0 6
PT 100/PTC KTY81-121	-200... +850°C/-55... +150°C	0 7
PT 1000/NTC 103-AT2	-200... +850°C/-50... +110°C	0 8
Linear 0... 60 mV		0 9
Linear 12... 60 mV		1 0
Linear 0... 20 mA (this selection forces Out 4 = TX)		1 1
Linear 4... 20 mA (this selection forces Out 4 = TX)		1 2
Linear 0... 5 V		1 3
Linear 1... 5 V		1 4
Linear 0... 10 V		1 5
Linear 2... 10 V		1 6
TC J	-58... +1832°F	1 7
TC K	-58... +2498°F	1 8
TC S	-58... +3200°F	1 9
TC R	-58... +3200°F	2 0
TC T	-94... +752°F	2 1
Infrared J	-58... +1445°F	2 2
Infrared K	-58... +1445°F	2 3
PT 100/PTC KTY81-121	-328... +1562°F/-67... +302°F	2 4
PT 1000/NTC 103-AT2	-328... +1562°F/-58... +230°F	2 5

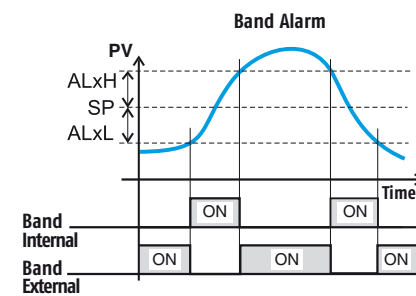
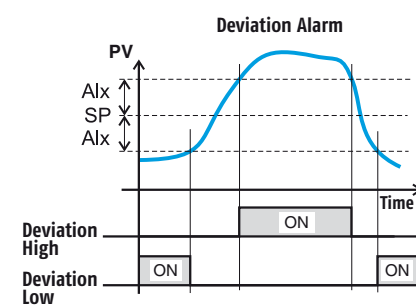
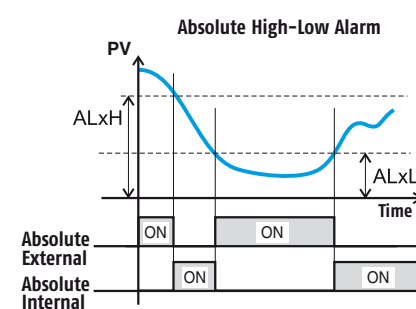
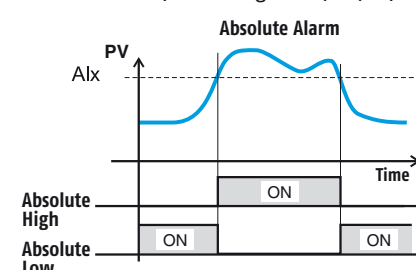
Control mode	OP1	OP2	OP3	OP4	N	O
ON/OFF heating = H	H	AL1	AL2	AL3	0	0
ON/OFF cooling = C	C	AL1	AL2	AL3	0	2
ON/OFF with neutral zone (H/C)	H	C	AL2	AL3	0	4
PID heating = H	H	AL1	AL2	AL3	1	0
PID cooling = C	C	AL1	AL2	AL3	1	2
PID double action (H/C)	H	C	AL2	AL3	1	4
	H	AL1	AL2	C	1	5
	C	H	AL2	AL3	1	6
	H	C	AL2	C	1	7
	C	H	AL2	H	1	8
	H	C	AL2	H	1	9

Alarm 3	Alarm 2	Alarm 1	P	Q	R
Not used			0	0	0
Sensor break			1	1	1
Absolute			2	2	2
Absolute High/Low			3	3	3
Deviation			4	4	4
Band			5	5	5
			6	6	6
			7	7	7
			8	8	8
			9	9	9

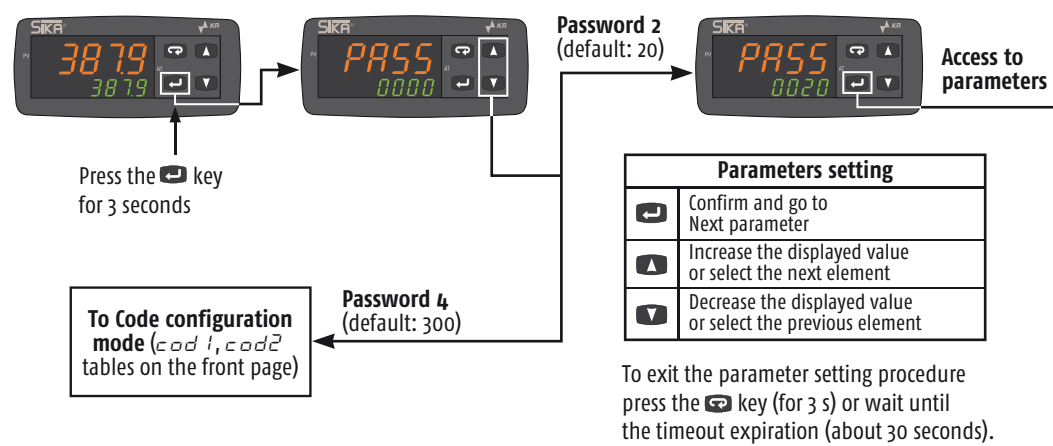
Service functions activation	S
None	0
Wattmeter (instantaneous power expressed in kW) (note 1)	1
Wattmeter (Power consumption expressed in kWh/h) (note 2)	2
Absolute worked time (expressed in days) (note 3)	3
Absolute worked time (expressed in hours) (note 3)	4

- Notes:
1. **Wattmeter Instantaneous power** is continuously computed as multiplication of the Load Voltage, Load Current parameter values and the controller output instantaneous value.
 2. **Wattmeter power consumption** is the estimated hourly energy consumption (using Load Voltage and Load Current parameter values), computed on the previous 15 minutes period. The readout is updated every 15 minutes.
 3. **Worked Time counter** is continuously increased when the controller is turned ON.

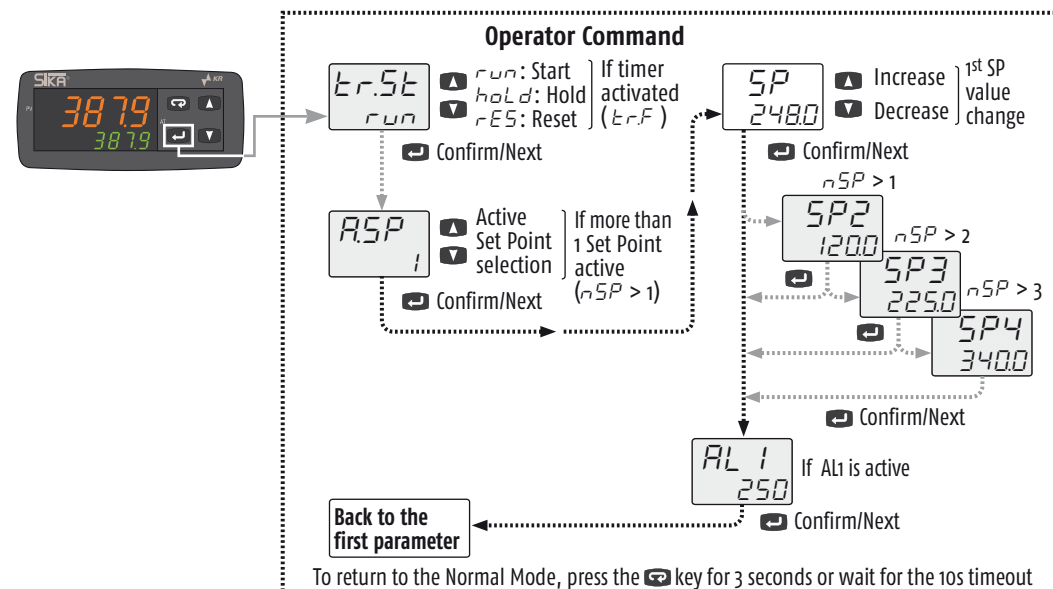
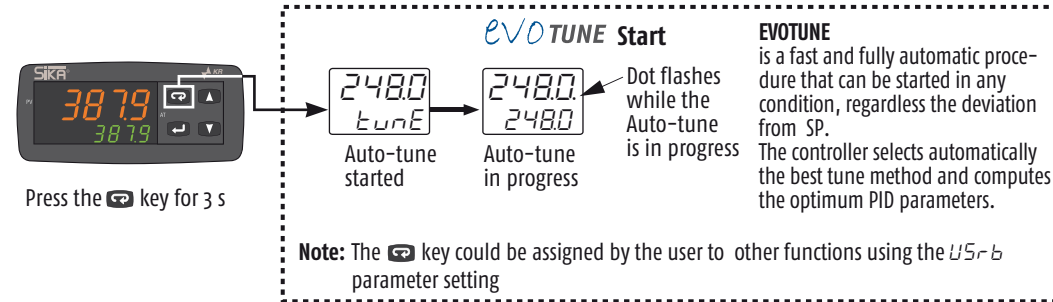
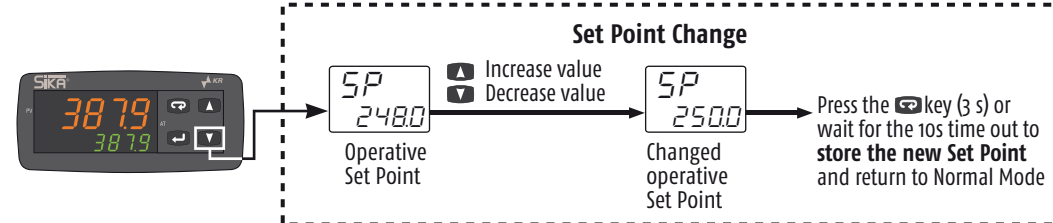
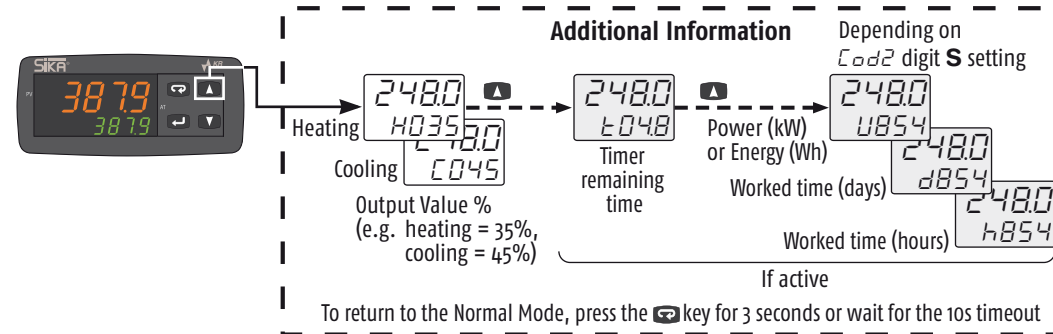
ALARM TYPES (Cod2 digits: P, Q, R)



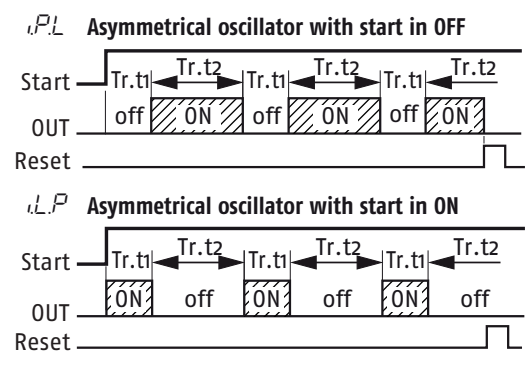
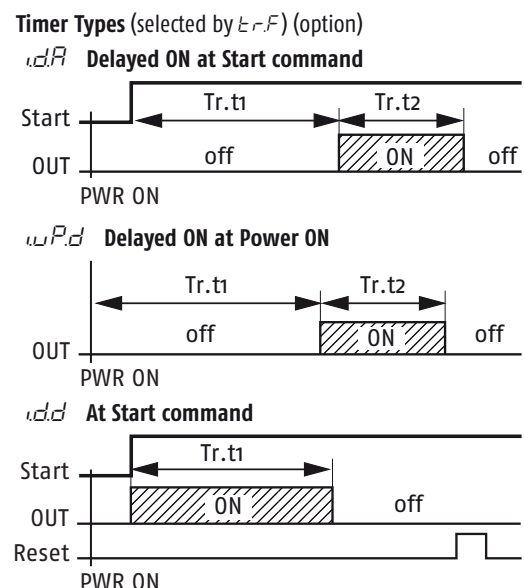
PARAMETERS SETTING



CONTROLLER OPERATION



FUNCTION SELECTION



Parameters List (*PASS*: 20) (in gray the parameters related to optional features)

Group	Param.	Description	Range value or selection list elements	Default	User value	Note
Commands	<i>trSt</i>	Timer status				Option
	<i>oPEr</i>	Operative Mode Selection	reg = Auto, oplo = Manual, stdy = Standby			
	<i>ASP</i>	Set Point Selection	0 = SP, 1 = SP2, 2 = SP3, 3 = SP4	0 = SP		
	<i>tunE</i>	Start Auto Tune	0 = OFF, 1 = start	0 = OFF		evoTUNE
Control	<i>Pb</i>	Proportional Band	1... 9999 (Engineering Units = E.U.)	20		
	<i>tI</i>	Integral Time	0... 10000 s	200		<i>cod1</i> Digit N = 1
	<i>tD</i>	Derivative Time	0... 1000 s	50		
	<i>HSEt</i>	Hysteresis ON/OFF Control	0... 9999 (E.U.)	1		<i>cod1</i> Digit N = 0
	<i>tCH</i>	Heating output cycle time	0.1... 130 s	20.0		<i>cod1</i> Digit N = 1
	<i>rCG</i>	Relative Cooling Gain	0.01... 99.99	1.00		<i>cod1</i> Digit N = 1 <i>cod1</i> Digit O > 4
	<i>tCC</i>	Cooling output cycle time	0.1... 130 s	20.0		<i>cod1</i> Digit N = 1 <i>cod1</i> Digit O > 1
Set Point	<i>SP</i>	Set Point 1				
	<i>SP2</i>	Set Point 2				If <i>nSP</i> > 1
	<i>SP3</i>	Set Point 3				If <i>nSP</i> > 2
	<i>SP4</i>	Set Point 4				If <i>nSP</i> > 3
	<i>SPLL</i>	Set Point min. Value	-1999... SPHL (E.U.)			
	<i>SPHL</i>	Set Point max. Value	SPLL... 9999 (E.U.)			
Alarms	<i>nSP</i>	No. of Set Points	1... 4	1		
	<i>AL1</i>	Alarm 1 threshold	AL1L... AL1H			
	<i>AL1L</i>	Alarm 1 low threshold/Low limit		-1999		If digit P of <i>cod2</i> is > 1
	<i>AL1H</i>	Alarm 1 high threshold/High limit		9999		
	<i>HAL1</i>	AL1 hysteresis	1... 9999 (E.U.)	1		
	<i>AL2</i>	Alarm 2 threshold	AL2L... AL2H			
	<i>AL2L</i>	Alarm 2 low threshold/Low limit		-1999		If digit Q of <i>cod2</i> is > 1
	<i>AL2H</i>	Alarm 2 high threshold/High limit		9999		
	<i>HAL2</i>	AL2 hysteresis	1... 9999 (E.U.)	1		
	<i>AL3</i>	Alarm 3 threshold	AL3L... AL3H			
	<i>AL3L</i>	Alarm 3 low threshold/Low limit		-1999		If digit R of <i>cod2</i> is > 1
	<i>AL3H</i>	Alarm 3 high threshold/High limit		9999		
Soft Start	<i>SSP</i>	Soft Start Output value	-100... 100%	0		
	<i>SSt</i>	Soft Start Time	0.00... 8.00 (hh.mm)	0		
	<i>SSc</i>	Low Scale readout	-1999... 9999	-1999		For linear Input types only
Input	<i>FSc</i>	High Scale readout	-1999... 9999	9999		
	<i>dP</i>	Number of decimals	0... 3 (linear inputs); 0... 1 (other inputs)	0		
	<i>FIL</i>	Measured value Digital filter	OFF; 0.1... 20.0 s	0 = OFF		
Timer	<i>trF</i>	Timer Type	nonE = Timer not used i.d.A = Delayed ON at start command i.uP.d = Activation ON at Power ON i.d.d = At start command i.P.L = Asymmetrical oscillator, start in OFF i.L.P = Asymmetrical oscillator, start in ON	none		Timer management (Start, Stop, Reset) can be done using the <i>trSt</i> command or the [Key] key (if programmed) or by the Dh/Dl2 digital inputs (if programmed).
	<i>trU</i>	Timer Units	0 = hh.mm 1 = mm.ss 2 = sss.d	1 = mm.ss		
	<i>trt1</i>	Time 1	00.01... 995.9	1.00		digital inputs (if programmed).
<i>trt2</i>	Time 2	00.00... 995.9	1.00			
I/O	<i>io4F</i>	I/O 4 Function	ON = Transmitter Power Supply OUT4 = SSR out Di2C = Dig. In. from contact Di2U = 24 VDC Digital Input	ON		
Digital Inputs	<i>dIF1</i>	Digital Input 1 Function	0... 21	0		See the Dh, Dl2 functions table
	<i>dIF2</i>	Digital Input 2 Function	0... 21	0		
	<i>dIA</i>	Digital Inputs Action	0 = Dh direct action, Dl2 direct action 1 = Dh reverse action, Dl2 direct action 2 = Dh direct action, Dl2 reverse action 3 = Dh reverse action, Dl2 reverse action	0		Dl2 only if configured
Display	<i>usrb</i>	Key [Key] Function	nonE, tunE, oplo, aac, asi, chsp, st.by, str.t	tunE		See the [Key] Key function table
	<i>dCL</i>	Colour of the Process Value display	0 = Change 1 = Red 2 = Green 3 = Orange	2		If Change, the colour is green if PV differs from SP less than <i>AdE</i> , red if higher than <i>AdE</i> and orange if is lower than <i>AdE</i>
	<i>AdE</i>	Display change color threshold (when <i>dCL</i> = 0)	0 (OFF)... 9999 (e.u.)			
Serial communications	<i>dSt</i>	Display Power OFF time (mm.ss)	OFF (display ON) 0.1... 99.59	OFF		
	<i>AdD</i>	Instrument Address	1... 254	1		Modbus RTU slave protocol
Wattmeter	<i>BRd</i>	Baud rate	1200, 2400, 9600 baud, 19.2, 38.4 kbaud	9600		
	<i>VolE</i>	Load Voltage	1... 999 (V)	230		If digit S of <i>cod2</i> is > 1
Password	<i>cur</i>	Load Current	1... 9999 (A)			
	<i>PAS4</i>	Configuration access Password	0... 999	300		
<i>PAS2</i>	Parameters access Password	0... 999	20			

Note: To access all the instrument features, please see the "Complete configuration procedure" in the "Engineering Manual". Complete Configuration and Parameter setting can be easily uploaded from the controller and downloaded to other controllers using the Configuration Key and Communication Adapter model: A-01.

dIF Digital Inputs Dh and Dl2 Functions

Code displayed	Description
0	Disabled (OFF) (default)
1	Alarm Reset
2	Alarm Acknowledge (ACK)
3	Hold of the measured value
4	Stand by mode
5	Manual Mode
6	Heat with "SP" and Cool with "SP2"
7	Timer Run/Reset [on transition]
8	Timer Run [on transition]
9	Timer Reset [on transition]
10	Timer Run/Reset
11	Timer Run/Reset
12	Timer Run/Reset with lock at the end of the time count
18	Sequential Set Point selection [on transition]
19	SP/SP2 selection
20	Binary coding for Set Point selection on Dh and Dl2 (00 = SP, 01 = SP2, 10 = SP3, 11 = SP4)
21	Digital inputs in parallel to the [Up] and [Down] keys (Dh1 = [Up] , Dh2 = [Down])

usrb Key **[Key]** Function

Code displayed	Description
nonE	Not used
<i>tunE</i>	Starts auto tuning functions (default)
<i>oPLo</i>	Manual mode
<i>ARc</i>	Alarm Reset
<i>AS</i>	Alarm Acknowledge
<i>chSP</i>	Circular Set Point Selection (shows SP, SP2, SP3)
<i>Stby</i>	Stand-by mode
<i>StE</i>	Starts/Stop/Reset timer